An environment for virtual experimentation with computational models based on P systems

PhD dissertation by Luis Valencia Cabrera

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- Introduction
- Core
- 3 Applications
- 4 Conclusions





- Introduction
 - Motivation
 - Models in real life
 - Bio-inspired Computing
- Core
- Applications
- Conclusions





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Motivation

Starting point

- There is nothing more practical than a good theory, but...
- There is nothing more enriching for a theory than putting it into practice.

What about Membrane Computing?

- Theory supported by solid foundations.
- Modelling and Simulation tools play an important role.





Purpose

General goals

- Providing an integrated methodology for the practical use of solutions based on Membrane Computing:
 - Problem → solution.
- Developing software tools to support this methodology, helping:
 - P systems designers.
 - End users.
- Applying methodology and tools to solve relevant theoretical and real-life problems.





Context

- This work falls within Natural Computing.
- More specifically, Membrane Computing.
- Computer-aided modelling, simulation and verification.





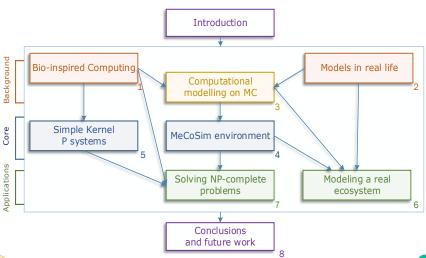
PhD thesis contribution

- Methodology from problem to end user solution.
- MeCoSim (environment and plugins):
 - IDE for P systems designers.
 - End-user visual applications.
- Solutions to relevant problems (NP-hard and real-life).





Overview - General outline







- Introduction
 - Motivation
 - Models in real life
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The need for model designing

Real-life complexity

- Many phenomena in real world are **complex** dynamic **systems**.
- A suitable way to analyze them is by modelling.

Model

Concrete, abstract, graphical or formal representation to study, analyze, explain and reason about a system (simplified image).

- Intrinsic to any scientific activity.
- Formal models: important achievements when converging Biology, Computer Science, etc. (multidisciplinary approach).





Formal models

Formal model

Abstraction of a specific aspect of the world onto a mathematical domain.

Features of a good model¹

- Relevance.
- Understandability.
- Extensibility.
- Mathematical-computational tractability.

Computational modelling and simulation are in the core of modern scientific method.

¹Regev, A., Shapiro, E. Cellular abstractions: Cells as computations. *Nature* **419**, 6905 (2002), 343-343.

Some approaches

Modelling approaches

- ODEs/PDEs.
- Agent based systems.
- Petri nets.
- Process algebra, π -calculus.





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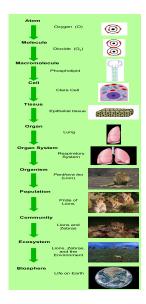


Getting inspired by Nature

Natural Computing

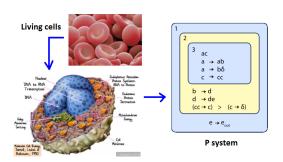
Analysis, design and implementation of processes that can be considered as calculation procedures.





Membrane Computing

- Inspired by the structure and functioning of living cells.
- Machine-oriented computational paradigm.
 - Solid theoretical foundations (formalization and computational complexity).
 - Solutions to theoretical or practical problems.







P systems frameworks

Main classical frameworks

- Cell-like P systems.
- Tissue-like P systems.
- Spiking Neural P systems.

More recent frameworks

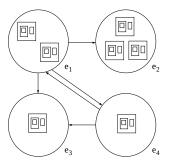
- Multienvironment P systems.
- Kernel P systems.





Multienvironment P systems I

- Environments containing P systems.
- Communication among environments.
- Computable functions associated with rules.
- Semantics: max. parallel, non deterministic and synchronized.







Multienvironment P systems II

Definition

A multienvironment P system of degree (q, m, n) $(q, m, n \ge 1)$ and with $T \ge 1$ time units is a tuple

$$(G, \Gamma, \Sigma, \mu, \tau, \Pi_1, \dots, \Pi_n, \mathcal{R}, E_1, \dots, E_m, \mathcal{R}_E)$$

where:

- G = (V, S) is a directed graph. Let $V = \{e_1, \dots, e_m\}$.
- Γ and Σ are alphabets such that $\Sigma \subsetneq \Gamma$.
- μ is a rooted tree with q nodes (called membranes) injectively labelled by elements from the set $\{1,\ldots,q\} \times \{0,+,-\}$. If the label of a membrane is (i,α) , then such a membrane will be denoted as $[]_i^\alpha$ and we will say that the membrane has label i and electrical charge α . The root of the tree has 1 as associated label.
- T is a natural number.
- For each $k, 1 \leq k \leq n$, $\Pi_k = (\Gamma, \mu, \mathcal{M}_{1,k}, \dots, \mathcal{M}_{q,k}, \mathcal{R})$ are P systems of degree q such that: (a) all of them have the same membrane structure μ ; (b) $\mathcal{M}_{1,k}, \dots, \mathcal{M}_{q,k}$ are finite multisets over Γ (initial multisets); and (c) \mathcal{R} is a finite set of rules of the form $r \equiv u[v]_i^{\alpha} \xrightarrow{t_i} u'[v']_i^{\alpha'}$, where $u, v, u', v' \in \mathcal{M}_t(\Gamma)$, $u+v \neq \emptyset$, $1 \leq i \leq q$ and $\alpha, \alpha' \in \{0,+,-\}$. Each rule r from the P system has an associated computable function f_r whose domain is $\{1,\dots,T\}$.

Multienvironment P systems III

Definition (cont.)

- E_1, \ldots, E_m are finite multisets over Σ .
- \mathcal{R}_{F} is a finite set of rules of the form

$$(x)_{e_j} \xrightarrow{\rho_r} (y_1)_{e_{j_1}} \cdots (y_h)_{e_{j_h}} \quad \text{y} \quad (\Pi_k)_{e_j} \xrightarrow{\rho_{r'}} (\Pi_k)_{e_{j'}}$$

where $x, y_1, \ldots, y_h \in \Sigma$, $(e_j, e_{j_i}) \in S$, $1 \le l \le h$, $(e_j, e_{j'}) \in S$, $1 \le j, j' \le m$, $1 \le k \le n$ and $p_r, p_{r'}$ are computable functions whose domain is $\{1, \ldots, T\}$. Moreover:

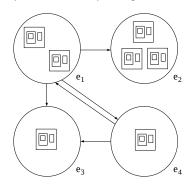
• If $(x)_{e_j} \stackrel{p_r}{\longrightarrow} (y_1)_{e_h} \cdots (y_h)_{e_{j_h}}$ is a rule in \mathscr{R}_E , then there cannot exist any rule in \mathscr{R} whose left-hand side is of the form $u[v]_1^\alpha$ with $x \in u$.





Multicompartmental P systems I

- Stochastic approach.
- Initially, P systems are randomly distributed among environments.
- Computable functions: propensities.
- P systems and objects can be sent to other environments.
- Semantics: multicompartmental Gillespie's algorithm.







Multicompartmental P systems II

Definition

A multicompartmental P system of degree (q, m, n) $(q, m, n \ge 1)$ having $T \ge 1$ time units is a multienvironment P system of degree (q, m, n) and with T time units

$$(G, \Gamma, \Sigma, \mu, \tau, \Pi_1, \dots, \Pi_n, \mathcal{R}, E_1, \dots, E_m, \mathcal{R}_E)$$

which fulfills the following conditions:

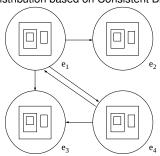
- The computable functions associated to the rules of the environment and the rules of the P systems are the propensities of such rules. These functions are determined from the values of stochastic constants, by applying the mass action law. The stochastic constants associated with each rule are calculated, on their turn, from the values of kinetic constants which have been experimentally calculated. The propensities are functions which depend on time, but on the other hand, they do not depend on the environment e_j where the corresponding P system currently is.
- At the initial instant, the *n* P systems are randomly distributed among the *m* environments of the system.
- For every rule of type $(x)_{e_j} \stackrel{p_r}{-} (y_1)_{e_{j_1}} \cdots (y_h)_{e_{j_h}}$, we have h=1; that is, an object x can just move from an environment to another one, possibly getting transformed into another object y_1 .





PDP systems I

- Probabilistic approach.
- Initially, each environment holds a single P system.
- Computable functions: probabilities.
- Only objects can be sent to other environments.
- Semantics:
 - DNDP: Direct Non-Deterministic distribution with Probabilities.
 - DCBA: Direct distribution based on Consistent Blocks Algorithm.







PDP systems II

Definition

A Population Dynamics P System (PDP system) of degree (q, m), where $(q, m \ge 1)$ and having $T \ge 1$ time units is a multienvironment P system of degree (q, m, m) and with T time units

$$(G,\Gamma,\Sigma,\mu,\tau,\Pi_1,\ldots,\Pi_m,\mathcal{R},E_1,\ldots,E_m,\mathcal{R}_E)$$

satisfying the following conditions:

- At the initial instant, each environment e_j contains exactly one P system, which will be denoted by Π_j. Therefore, the number of P systems matches the number of environments.
- Functions p_r associated with rules from \mathcal{R}_F of the type

$$(x)_{e_j} \xrightarrow{p_r} (y_1)_{e_{j_1}} \cdots (y_h)_{e_{j_h}}$$

have their range included in [0,1] and they verify:

- For each $e_j \in V$ and $x \in \Sigma$, the sum of the functions associated with rules of the above type is the constant function 1.
- Functions p_{,f} associated with rules from R_E of the type (Π_k)_{ej} P_{,f} → (Π_k)_{ef} are all constant and equal to 0; that is, one may as well assume that this type of rule is forbidden, or equivalently, P systems residing in an environment cannot travel to any other environment.
- For each rule $r \in \mathscr{R}$ of the system Π_j located in e_i , $1 \le j \le m$, the computable function f_r also depends on the environment (thus, it will be denoted as $f_{r,j}$) and its range is contained within [0,1]. Moreover, for each $u,v \in M_r(\Gamma)$, $1 \le i \le q$ and α , $\alpha' \in \{0,+,-\}$, the sum of the functions $f_{r,j}$ with $r \equiv u[v]_i^\alpha \to u'[v']_i^{\alpha'}$, is the constant function 1.

Kernel P systems I

Purpose

- Need of an integrative model with the most relevant syntactic and semantic ingredients of different P systems.
- Relatively low level, defined in an operational style.
- Two-fold intention:
 - Flexible to solve many problems from a core (kernel).
 - Uniform platform for computational modelling, simulation and verification of models based on P systems.

Basic components

- Compartments in a dynamic non directed graph.
- Types of compartments defining sets of guarded rules and execution strategies.

Kernel P systems II,

Definition

T is a set of compartment types, $T = \{t_1, \dots, t_s\}$, where $t_i = (R_i, \sigma_i)$, $1 \le i \le s$, consists of a set of rules, R_i , and an execution strategy, σ_i , defined over $Lab(R_i)$, the labels of the rules of R_i .

Definition

A kernel P (kP) system of degree n is a tuple

$$k\Pi = (A, \mu, C_1, \ldots, C_n, i_0),$$

where A is a finite set of elements called *objects*; μ defines the *membrane structure*, which is a graph, (V, E), where V are vertices indicating components, and E edges; $C_i = (t_i, w_i)$, $1 \le i \le n$, is a *compartment* of the system consisting of a compartment type from T and an *initial multiset*, w_i over A; i_o is the *output compartment* where the result is obtained.

Kernel P systems III

Definition

If g is the abstract relational expression γa^n and the current multiset is w, then the guard denotes the relational expression $\#_a(w)\gamma n$. The guard g is true for the multiset w if $\#_a(w)\gamma n$ is true.

Definition

If g is the abstract Boolean expression and the current multiset is w, then the guard denotes the Boolean expression for w, obtained by replacing abstract relational expressions with relational expressions for w. The guard g is true for the multiset w when the Boolean expression for w is true.

Definition

A guard is: (i) one of the Boolean constants *true* or *false*; (ii) an abstract relational expression; or (iii) an abstract Boolean expression.





Kernel P systems IV

Definition

A rule from a compartment $C_{l_i} = (t_{l_i}, w_{l_i})$ can have one of the following types:

- (a) **rewriting and communication** rule: $x \to y \{g\}$, where $x \in A^+$ and y, has the form $y = (a_1, t_1) \dots (a_h, t_h)$, $h \ge 0$, $a_j \in A$ and t_j indicates a compartment type from T see Definition 5 with instance compartments linked to the current compartment; t_j might indicate the type of the current compartment, i.e., t_j in this case it is ignored; if a link does not exist (the two compartments are not in E) then the rule is not applied; if a target, t_j , refers to a compartment type that has more than one instance connected to t_i , then one of them will be non-deterministically chosen;
- (b) structure changing rules; the following types are considered:
 - (b1) **membrane division** rule: $[x]_{t_{i_{j}}} \rightarrow [y_{1}]_{t_{i_{1}}} \dots [y_{p}]_{t_{p}} \{g\}$, where $x \in A^{+}$ and y_{i} has the form $y_{i} = (a_{j,1}, t_{j,1}) \dots (a_{j,h_{j}}, t_{j,h_{j}})$ like in rewriting and communication rules; the compartment t_{i} will be replaced by p compartments; the j-th compartment, instantiated from the compartment type $t_{i_{j}}$ contains the same objects as t_{i} , but x, which will be replaced by y_{j} ; all the links of t_{i} are inherited by each of the newly created compartments;
 - (b2) **membrane dissolution** rule: $[]_{i_l} \to \lambda \ \{g\};$ the compartment l_i will be destroyed together with its links;
 - (b3) link creation rule: $[x]_{t_i}$; $[]_{t_j} o [y]_{t_i} []_{t_j}$ $\{g\}$;
 - the current compartment is linked to a compartment of type t_{i_j} and x is transformed into y; if more than one instance of the compartment type t_{i_j} exists then one of them will be non-deterministically picked up; g is a guard that refers to the compartment instantiated from the compartment type t_{i_k} ;
 - (b4) **link destruction** rule: $[x]_{t_i} \prod_{t_j} \rightarrow [y]_{t_j}$; $\prod_{t_j} \{g\}$; is the opposite of link creation and means that the compartments are disconnected.

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 - Simple kernel P systems
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Implementation vs simulation

- Designs for the abstract machines have been provided.
- No implementation (real machines).
- Simulation of the abstract machines on electronic devices is possible, complementing:
 - Computational power and efficiency studies.
 - Formal verification and validation of properties.
 - Manual traces of the abstract model computation.





Simulation trends in Membrane Computing

Specific purpose. A problem

- Ad-hoc simulators.
- Focus: solution to a specific problem/instance.



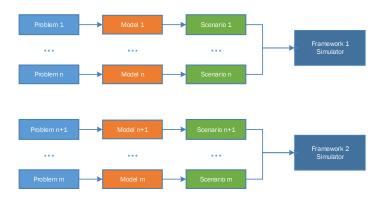




Simulation trends in Membrane Computing

Framework oriented

- A wider range of problems, within a **specific framework**.
- MetaPlab, Infobiotics Workbench, etc.



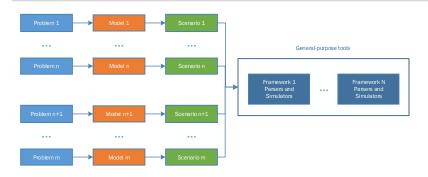




Simulation trends in Membrane Computing

General purpose tools

- Global scope (many frameworks within Membrane Computing).
- P-Lingua framework².



²Developed by the Research Group on Natural Computing.

P-Lingua

Parsers and simulators

- Cell-like P systems.
- Tissue-like P systems.
- Spiking Neural P systems.
- PDP systems.
- Simple kernel P systems.

Features to review

- High coupling instance solution in a file.
- No high level interface for P systems designers.
- Focus on P systems designer, not on end user.

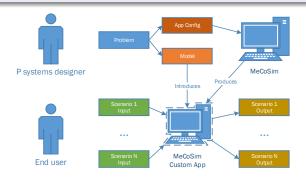




MeCoSim (Membrane Computing Simulator)

Goals

- For P systems designers: modelling, edition, testing, debugging, simulation, analysis and visualization of P systems; delivery of end-user applications.
- For end users: custom applications (black boxes), to enter inputs, run virtual experiments and get results.
- Required features: flexibility, extensibility.







Custom applications

Origin

- Development of ad-hoc visual applications for different ecosystems in RGNC.
- Detection of general needs.

Definition of a custom application

- Visual arrangement.
- Input tables to introduce data.
- Parameters generation for the model/solution.
- Outputs to show (tables/charts/graphs).

Custom app. Main functionalities

- Modelling and edition of solutions (P-Lingua files).
- Debugging.
- Visualization of alphabet, membrane structure and multisets.
- Virtual experimentation by simulating (halting or number of steps).





MeCoSim plugins

A plugins architecture has been implemented in MeCoSim.

Plugins developed within this thesis

- MeCoSim basics.
- Processes.
- Graphs.
- Languages Integration.
- Daikon.
- Promela.
- SAT.





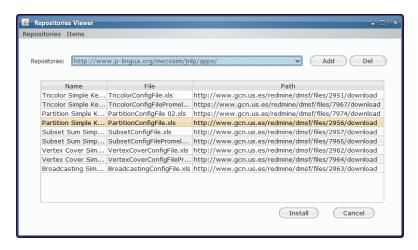
Repositories

System of repositories

- Plugins.
- Apps.
- Models.
- Scenarios.

Example - apps.xml

Repositories







Luis Valencia Cabrera (RGNC-CCIA)

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Methodology

Integrated methodology

- From: initial study of a problem.
- To: solution (a custom application).
- Through: computational modelling tools based on P systems.
- Supported by: MeCoSim, on top of P-Lingua.

Types of problems

- Real-life problems, complex systems as population dynamics.
- NP-hard problems, e.g. SAT or 3-COL.





Methodology

Main stages

- Modelling.
- Simulation.
- Customization.
- Debugging.
- Visualization and data analysis.
- Invariants detection.
- Properties verification.





Modelling

Providing a **solution** or **model**, depending on the type of problem under study.

Steps

- Goal and scope.
- Study of the problem.
- Abstraction. It may imply:
 - Processes and interactions.
 - Parameters.
 - Sequencing/parallelization.
- Solution/model by P systems.
- Traces.





Simulation I

Purpose

- Input: a model based on P systems.
- Result: the simulation of the model.
- Requirements:
 - Description of the system.
 - Input data.
 - Simulator.





Simulation II

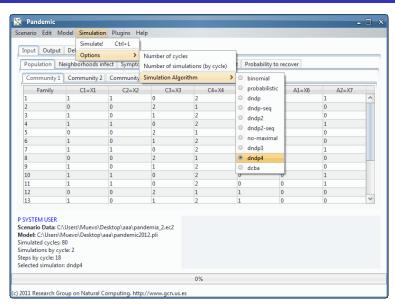
Support

- Description → P-Lingua language and parsers.
- Input → P-Lingua files or MeCoSim custom apps.
- Simulator → MeCoSim environment + P-Lingua or external simulator.





Simulation III







Customization I

Purpose

- Every problem deals with different data:
 - Input data, describing instances.
 - Expected output results.
- Goal: custom application, providing:
 - Black box for end-user virtual experiments.
 - Usability for P systems designers.





Customization II

Support

- Custom apps generation → MeCoSim.
- Custom elements, as shown before:
 - Arrangement of inputs and outputs.
 - Input tables.
 - Parameters generation.
 - Output results (tables, charts, graphs).





Debugging

Purpose

- Check syntactic correctness.
- Analyze the dynamics of the system:
 - Observing the evolution of the system.
 - Testing matching with expected behavior.

Errors detection (iterative process)

- Theoretical model.
- Computational description.
- Simulators.





Visualization and data analysis I

Purpose

- Analysis of P systems for designers.
- Data analysis of parts of the system output, post-processing.
 - Aggregation.
 - Basic descriptive statistics.
 - Charting to analyze evolution or distribution of elements.





Visualization and data analysis II

Support

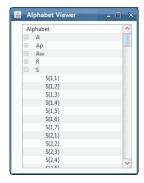
- Viewers for structures and elements of P systems configurations.
- Custom outputs. Post-processed, filtered and aggregated outputs.
- Charts generation.
- Graphs.

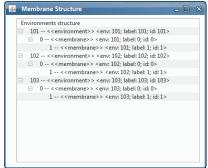




Visualization and data analysis III

Advanced visualization of structures I



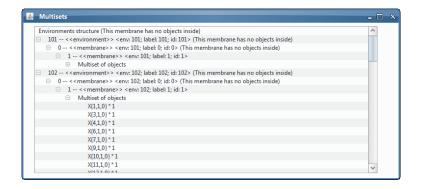






Visualization and data analysis IV

Advanced visualization of structures II







Visualization and data analysis V

Graphs visualization I

Graphs

A plugin was developed to generate graphs from parameters, oriented to:

- Designers: P system inner structure.
- End users: Information coded in the solution to the problem itself.

Options for:

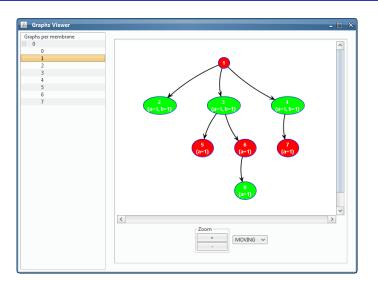
- Simple graph or tree.
- Tree view of a set of graphs or trees.





Visualization and data analysis VI

Graphs visualization II







Invariants detection I

Purpose

- Solutions and models may present interesting properties.
- Not easy to detect manually.
- Goal: automatic invariants detection.





Invariants detection II

Support

MeCoSim custom outputs focusing specific data.

Languages and Software Engineering of the University of Washington

- MeCoSim Daikon plugin³ configuration for extracting traces from outputs.
- Daikon invariants detector⁴ analyzing traces to detect invariants.

³Daikon and Promela plugins developed in collaboration with the Department of Mathematics and Computer Science, University of Pitesti, and the Department of Computer Science, University of Sheffield ⁴Daikon: implementation of dynamic detection of likely invariants, developed by the Programming

Properties verification I

Purpose

- Input:
 - A design of a P system based model/solution.
 - Syntactically and semantically correct.
 - (Opt.) Previous manual definition and verification of properties.
- Goal: automatic verification of properties. May use model checking techniques.

Properties verification II

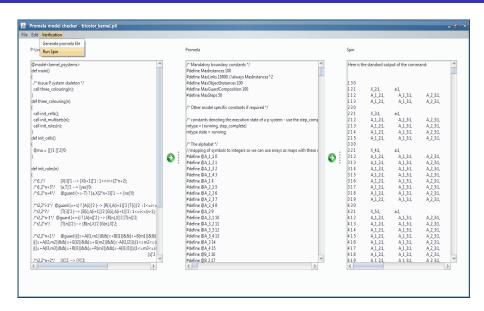
Support

- MeCoSim integration with tools for formal verification:
 - Promela⁵ code generation from MeCoSim.
 - Properties definition can be added to generated Promela file.
 - Spin⁶ model checker runs from Promela code.

⁵**Promela** (Process Meta Language): modelling language accepted by Spin model checker.

⁶Spin model checker: software for automatic formal verification of multi-threaded applications, developed at Bell Labs in the Unix group of the Computing Sciences Research Center, starting in 1980.

Properties verification III



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Simple kernel P systems

Simple kernel P systems

Simplified version of Kernel P systems

- Only rewriting-communication and division rules.
- Only maximal parallelism as execution strategy.





Definition

A simple kernel P system of degree $n \ge 1$ is a tuple

$$\Pi = (\Gamma, \mathcal{E}, T, G, C_1, \dots, C_n, i_{out})$$

where

- Γ is a finite alphabet whose elements are called objects.
- \mathscr{E} is an alphabet contained in Γ (called output alphabet).
- $T = \{t_1, \dots, t_s\}$ is a set of types of compartment.
- G = (V, E) is a non directed graph.
- $V = \{C_1, \dots, C_n\}$ is the set of nodes in the graph, called compartments of the system, such a way that $C_i = (t_i, w_i), 1 \le i \le n$, with $t_i \in T$ and $w_i \in M_I(\Gamma)$.
- i_{out} ∈ {0,1,...,n} is a number representing the environment (if i_{out} = 0) or a compartment of the system, if i_{out} ∈ {1,...,n}.

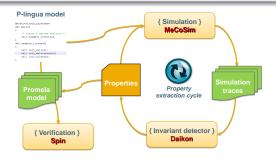




Software tools for simple kernel P systems

Tools developed within this thesis

- A framework for modelling, simulation and verification.
- An extension of P-Lingua language and parser for simple kernel P systems.
- Simulators: (1) In P-Lingua; (2) External (Spin)³, integrated with MeCoSim.



⁷In collaboration with the Department of Mathematics and Computer Science, University of Pitesti, and the Department of Computer Science, University of Sheffield

A language for simple kernel P systems I

Guards:

A rule
$$a \rightarrow b$$
 $\{=a^2\}$ is defined as:
@guard $\{=+a*2\}$? [a --> b];

Initialization of compartments:

$$@mu(0) = [c*3]'1;$$

Definition of initial multisets:

Associated with each specific compartment:

$$@mu = [[a*2]'1[b]'2[c*2]'0;$$

Associated with all the compartments of a certain type:

$$0ms(1) = x;$$

 $0ms(2) = y*3;$

A language for simple kernel P systems II

- New rule types in P-Lingua:
 - Rewriting and communication rules:

```
@guard g ? [a]'t_0 \rightarrow [a_1]'t_1, \ldots, [a_h]'t_h
```

Division rules:

```
@guard g ? [a]'t | -> [v_1]'t_{j_1}, \ldots, [v_p]'t_{j_p};
```

Both types of rules admit internal iterators:

$$[a]'1 \rightarrow [b]'2 &{[c,d{i}]'{i}}:{3 <= i <= n};$$

- Internal iterators:
 - Over multisets: & { multiset } : { index_ranges }
 - ② Over compartments: & { [multiset] ' { label } } : { index_ranges }
 - Over guards:

```
& { \textit{guard} } : { \textit{index\_ranges} } , for conjunction, and
```

| { guard } : { index_ranges } , for disjunction.

Contents

- Introduction
- Core
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 - Solving NP-complete problems
 - Modelling of a real ecosystem
- 4 Conclusions





Contents

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Solving NP-complete problems

- Membrane Computing solve NP-hard problems.
- This power can **not** be **fully exploited** yet.
- Tools as MeCoSim can aid studies in:
 - Tasks of design, debug, simulation and traces analysis, verification, etc.
 - Practical use to solve relevant instances.





NP-complete problems in MeCoSim I

Problems studied

- Cell-like P systems with active membranes: SAT, Partition, Subset Sum, Knapsack.
- Tissue-like P systems with cell division: 3-COL (colorings), SAT.
- Tissue-like P systems with cell separation: SAT.
- Spiking-neural P systems: SAT.
- Simple kernel P systems: 3-COL, Partition, Subset sum, Vertex cover.



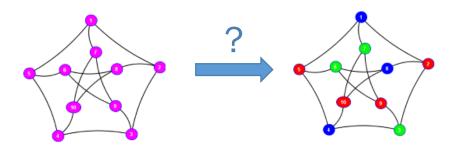


A solution for 3-COL problem based on simple kernel P systems I

3-COL problem

Given a non-directed graph, determine if a valid 3-coloring exists.

• Solve many practical problems (mainly in communication networks).



A solution for 3-COL problem based on simple kernel P systems II

Purpose

- Simple kernel P system solving the decision problem (yes/no).
- Solution based on a brute force algorithm:
 - Generation of colorings, based on division rules.
 - Checking, controlled by guards.
 - Output, sending yes/no to environment.

A solution for 3-COL problem based on simple kernel P systems III

Solution

A family of simple kernel P systems is considered:

$$\Pi = \{\Pi(n) : n \in \mathbb{IN}\}$$
, where $\Pi(n) = (\Gamma, IO, T, G, C_1, C_2, i_{out}, i_{in})$ is defined as follows:

• The working alphabet Γ is the following set:

$$\begin{array}{ll} \Gamma & = & \{A_1, \dots, A_n\} \cup \{A_{i,j} \mid 1 \leq i < j \leq n\} \cup \{T_1, \dots, T_n\} \cup \\ \{B_1, \dots, B_n\} \cup \{R_1, \dots, R_n\} \cup \{G_1, \dots, G_n\} \cup \\ \{a, s, X, Y, Z, yes, no\} \cup \{X_1, \dots, X_{2n+3}\} \end{array}$$

Where:

- A_i , $1 \le i \le n$, are symbols representing the *n* vertices in \mathcal{G} .
- $A_{i,j}$, $1 \le i < j \le n$, are symbols representing the possible edges in \mathscr{G} .
- T_i , $1 \le i \le n$, are symbols used in the process dividing compartments of type C_2 .
- B_i , R_i , G_i , $1 \le i \le n$, are symbols codifying the three colors (as in the case of tissue-like P systems).
- Symbol a is used only in compartment C_1 to select a single answer to be later sent to the environment.
- s, X, Y are symbols user in compartments of type C₂.
- Z is a symbol to be sent to compartment C_1 .
- yes, no are the possible answers: one of them will reach the environment from C₁ in the last step of the
 computation, as required by the decision problem.
- Symbols X₁,..., X_{2n+3} are used as a counter to control the maximum number of steps (2n+2) required
 by the only possible input from compartments of type C₂.

A solution for 3-COL problem based on simple kernel P systems IV

Solution (cont.)

- $10 = \{ yes, no \}.$
- $T = \{t_1, t_2\}$, with $t_1 = (R_1, \sigma_1)$ and $t_2 = (R_2, \sigma_2)$; that is, there exist two types of compartments t_1 and t_2 . The execution strategy $\sigma_1 = \sigma_2$ is the maximal parallelism with the constraint for each compartment to apply, at most, a division rule for each step of the computation. The sets of rules are the following:
 - R₁ is the set of rules:
 - * $r_{1,i}: X_i \to X_{i+1}, 1 \le i \le 2n+2.$
 - \star $r_{1,2n+3}: aZ \rightarrow (yes, 0).$
 - \star $r_{1,2n+4}: aX_{2n+3} \rightarrow (no,0) \{ \geq \overline{Z} \}.$

Rules $r_{1,i}$, $1 \le i \le 2n+2$ are responsible for counting the first 2n+2 steps; during that stage, for each solution found, an object Z is sent from C_2 to C_1 ; if one or more Z objects were received from compartments of type C_2 , that is, there exist at least one solution, then the compartment of type C_1 sends yes to the environment; otherwise, if no Z object has been received, after 2n+3 steps an object no is sent:

A solution for 3-COL problem based on simple kernel P systems V

Solution (cont.)

- R₂ is the following set of rules: Division rules:
 - * $r_{2,2i-1}: [A_i]_2 \to [R_iA_{i+1}]_2[T_i]_2 \{= s\}.$ * $r_{2,2i}: [T_i]_2 \to [B_iA_{i+1}]_2[G_iA_{i+1}]_2, 1 \le i \le n-1.$ * $r_{2,2n-1}: [A_n]_2 \to [R_nX]_2[T_n]_2 \{= s\}.$ * $r_{2,2n}: [T_n]_2 \to [B_nX]_2[G_nX]_2.$

These rules are applied at most in 2n steps, where all possible colorings are obtained for the n vertices. Rewriting and communication rules:

 \star $\mathit{r}_{2,2n+1}:s
ightarrow\lambda$ $\left\{ g
ight\}$ with g the following guard

$$=A_{1,2}=B_1=B_2 \vee =A_{1,2}=G_1=G_2 \vee =A_{1,2}=R_1=R_2 \vee \\ \vee \dots \dots \vee \\ =A_{n-1,n}=B_{n-1}=B_n \vee =A_{n-1,n}=G_{n-1}=G_n \vee =A_{n-1,n}=R_{n-1}=R_n$$

- * $r_{2,2n+2}: X \to Y$.
- * $r_{2,2n+3}: Ys \rightarrow (Z,1).$

A solution for 3-COL problem based on simple kernel P systems VI

Solution (cont.)

The guard appearing in rule $r_{2,2n+1}$ contains 3n(n-1)/2 terms and checks, for each pair $1 \le i < j \le n$, if the colors in nodes i and j is the same. If the current compartment contains object s, then that object is removed and, from that moment, no rule will be applied to that compartment. Rule $r_{2,2n+2}$ will transform X into Y once all possible calculation have finished. Rule $r_{2,2n+3}$ will be applied a solution is present in the current compartment of type C_2 , and will send object Z to the compartment with type C_1 .

- $G = (\{1,2\}, \{\{1,2\}\}).$
- $C_1 = (t_1, w_1), C_2 = (t_2, w_2), \text{ where } w_1 = aX_1, w_2 = A_1 \text{ s.}$
- $i_{out} = 0$; that is, the output of the system is codified in the environment.
- $i_{in} = 2$; that is, the input compartment is the initial C_2 .

It is important to note that instance $\mathscr{G}=(\mathscr{V},\mathscr{E})$ of 3-COL problem will be processed by the $\mathit{simple\ kernel\ P}$ system $\Pi(s(\mathscr{G}))$ with input multiset $\mathit{cod}(\mathscr{G})$.

A solution for 3-COL problem based on simple kernel P systems VII

Instances of 3-COL

Following two computable functions, s and cod, are defined over the set of instances of 3-COL problem as follows:

$$\left\{ \begin{array}{lcl} s(\mathcal{G}) & = & |\mathcal{V}| \\ cod(\mathcal{G}) & = & \{A_{i,j} : \{i,j\} \in \mathcal{E}, 1 \leq i < j \leq n\} \end{array} \right.$$

with $\mathscr{G}=(\mathscr{V},\mathscr{E})$ a non directed graph containing at least two vertices.





3-COL application

- P-Lingua file.
- Input tables for nodes and edges.
- Outputs for decision (yes/no) and colorings.
- Parameters for:
 - *n* (number of nodes), *m* (number of edges).
 - $e_{i,1}$ and $e_{i,2}$ (the two nodes of each edge i).
 - Parameters for generating coloring information.





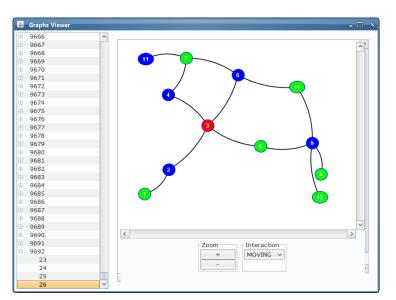
3-COL. Parameters

| Param Name | Param Value | Index 1 | Index 2 |
|------------|--------------------|-----------|---------|
| n | <2,1,1> | | |
| ne | <2,1,2> | | |
| e | <4,\$1\$,\$2\$> | [1ne] | [12] |
| nm | <@r,7> | | |
| m | <7,\$1\$,1> | [1nm] | |
| g | m{\$2\$} | [1@steps] | [1nm] |
| m | ne | | |
| versInfo | <,6,\$1\$,\$2\$> | [1<@r,6>] | [13] |
| versInfo2 | <,6,\$1\$,3-\$2\$> | [1<@r,6>] | [12] |
| versInfo2 | <,6,\$1\$,\$2\$> | [1<@r,6>] | 3 |





3-COL. Tree view of graphs







Generation of colorings in MeCoSim I

Focus: generation phase of 3-COL (confluence).

```
@model<tissue_psystems>
def main()
    call init cells();
    call init multisets(n);
    call init_rules(n);
def init cells()
    0mu = [[1'2]'0;
def init multisets(n)
    0ms(2) += A{i} : 1 <= i <= n;
def init rules(n)
   /* r1 */ [A{i}]'2 --> [R{i}]'2 [T{i}]'2 : 1<=i<=n;
    /* r2 */ [T{i}]'2 --> [B{i}]'2 [G{i}]'2 : 1<=i<=n;
```





Generation of colorings in MeCoSim II

- Solution: a family of P systems.
- Input: parameter n.
- Output: *number of cells* per step.
- Custom app.





Generation of colorings in MeCoSim III

| Tab Id | Tab Name | Tab Parent Id |
|--------|----------------|---------------|
| 1 | Tissue Example | 0 |
| 2 | Input | 1 |
| 3 | Size (n) | 2 |

| Table Id | Table Name | Tab Id | Columns | Init Rows | Save To File | Input / Output |
|----------|------------|--------|---------|-----------|--------------|----------------|
| 1 | Size (n) | 3 | 1 | 1 | TRUE | Input |

| Column Id | Column Name | Default Value | Editable | Tooltip | GraphicRole |
|-----------|-------------|---------------|----------|---------|-------------|
| 1 | Size | 3 | TRUE | n | |

Param Name Param Value







Generation of colorings in MeCoSim IV

| Result Table Id | Result Table Name | Table Id | Referred Table Id |
|-----------------|-------------------|----------|-------------------|
| 1 | CellsByStepAux | 0 | 0 |
| 2 | CellsByStep | 2 | 1 |

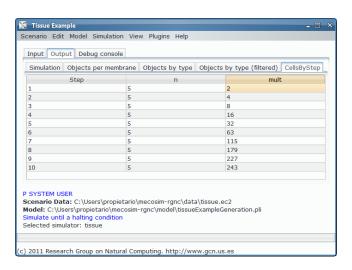
| Criteria Id | Select/Where/Group | Criteria | Formula | ReferredCriteria Id | Argument | Qualified Name | Where condition type | Where condition |
|-------------|--------------------|------------|---------|---------------------|----------|----------------|----------------------|-----------------|
| 1 | Select | step | | | | | | |
| 2 | Select | membranelD | | | | | | |
| 3 | WhereAux | membranelD | | | | | Integer | 0 |
| 4 | Where | formula | NOT | 3 | | | | |
| 5 | Group | step | | | | | | |
| 6 | Group | membranelD | | | | | | |

| Criteria Id | Select/Where/Group | Criteria | Formula | ReferredCriteria Id | Argument | Qualified Name | Where/Select condition type | Where condition |
|-------------|--------------------|------------|---------|---------------------|----------|-----------------------|-----------------------------|-----------------|
| 1 | Select | step | | | | | | |
| 2 | Auxiliary | parameter | n | | | | Integer | |
| 3 | Select | formula | CONVERT | 2 | INT | valn | DirectString | |
| 4 | Auxiliary | membranelD | | | | | - | |
| 5 | Select | formula | COUNT | 4 | | ncells | | |
| 6 | Group | step | | | | | | |





Generation of colorings in MeCoSim V

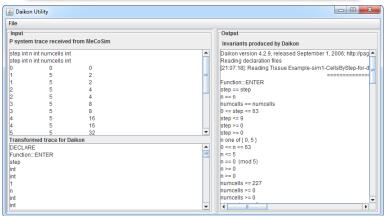






Generation of colorings in MeCoSim VI









Generation of colorings in MeCoSim VII

| Extraction | Result | Valid |
|--|------------------------------|-------|
| No. cells per step, 0 n | numcells = 2 ^{step} | true |
| No. cells per step $(n+1)\dots 2n$ | numcells = 3 (mod 4) | false |
| No. cells per step $(n+1)\dots(n+(n/2)+1)$ | numcells = 3 (mod 12) | false |
| No. cells last step , for different values of <i>n</i> put together | $numcells = 3^n$ | true |





Contents

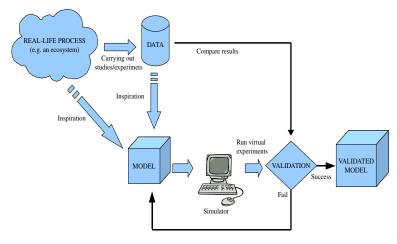
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Modelling protocol

Experimental validation

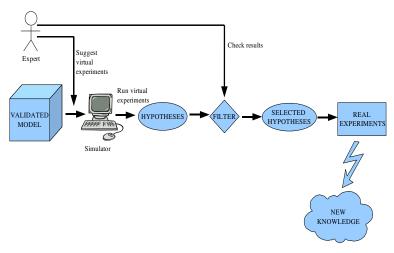






Modelling protocol

Virtual experimentation







Computational modelling of real ecosystems

Basic needs of ecologists

- Input:
 - Specific values for the parameters of the model.
 - Initial populations for each proposed scenario.
 - Environmental conditions.
- General mechanism for setting simulation parameters.
- Outputs generation and visualization.





Ecosystems and population dynamics problems studied I

Endangered species

- Bearded vulture (Catalan Pyrenees, Spain).
- Avian scavengers (Catalan Pyrenees, Spain).
- Scavengers birds (Catalan and Navarre Pyrenees, Spain, and Swaziland, South Africa).
- Newt (Calotriton asper, Sierra del Cadí, Spain).
- Amur Tiger (China).
- Giant Panda (captivity, Chengdu, China).





Ecosystems and population dynamics problems studied II

Others

- Hazel Grouse (reintroduction in the Pyrenees, Spain).
- Plant communities (Alt Pallars-Aran, Cerdanya-Alt Urgell, Cadí and Freser-Setcases, alpine and subalpine areas of Pyrenees, Spain).
- Pyrenean Chamois (pestivirus, Catalan Pyrenees, Spain).
- Amphibians (growth by random changes, Pi Valley stream, Sierra del Cadí, Spain).
- Pigs (animal production, Spain).
- Zebra Mussel (invasive species, reservoir of Ribarroja, Spain).
- Tritrophic interactions.
- Pandemics.





A real ecosystem: Zebra Mussel in Ribarroja

Context

- Zebra Mussel (Dreissena polymorpha): exotic invasive species.
- Important environmental and economical damage.
- In Spain since 2001, reservoir of Ribarroja, managed by Endesa S. A.

Purpose

- Knowledge about species+environment.
- Hypothesis about its introduction.
- Management tool to aid in decision making process:
 - By: managers designing strategies.
 - To: eradicate or decrease the population.





Zebra Mussel. Biology of the species

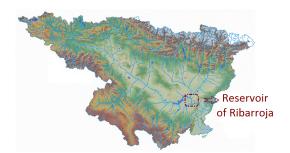
- Aquatic bivalve mollusc, dioecious species 1:1.
- High reproductive potential:
 - Depending on age (tens to hundreds of thousands).
 - Reproductive cycle depending on the temperature.
- High mortality rate from spawning to juvenile (up to 98%).
- Fast life cycle with two stages:
 - Larval phase (in water column, planktonic state).
 - Settled phase (young and adult, benthonic state).
- Huge mobility and great dispersal ability.
- Engineers of the ecosystem.





The reservoir of Ribarroja

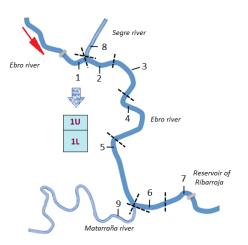
- Ebro River basin, Northeast of Spain.
- 35km length, variable depth up to 28m.
- Water from: rivers Segre and Matarraña, reservoir of Mequinenza.
- Regions with different temperature, conditions and substrate.
- Human interaction: managed by Endesa S. A., water flows, traffic of vessels.

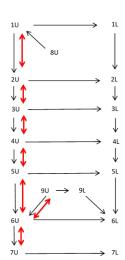






Areas inside the reservoir

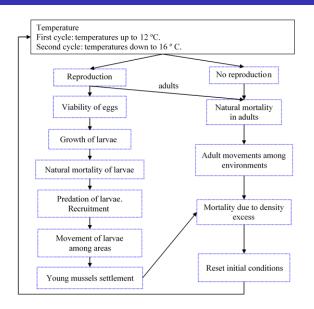








Processes and sequencing







Design of the model

Main aspects

- PDP system with 18 environments (areas of the reservoir).
- P systems skeleton structure: $\mu = [\]_1 \dots [\]_{39}\]_0$.
 - 1-20: first reproductive cycle.
 - 21-36: second reproductive cycle.
 - 37-38: Mortality depending on density of mussels.
 - 39: recruitment of larvae, depending on the population size.
- Rules influenced by many parameters.





Parameters of the model

Parameters

- Biology of the species (release of eggs, mortality rates, etc.).
- Environmental conditions:
 - General (temperature to start each reproductive cycle, proportion of eggs release per week, etc.).
 - Per area (temperature of the water per week, probability of reproduction per week, etc.).
- Properties of the area (dimensions, percentage of soil of each type, etc.).
- Human intervention (external inoculation, probability rates to move due to traffic of vessels, water renewal, etc.).





External inoculation

Rules

$$r_{e_{1,j}} \equiv (I_1 \rightarrow I^{LE_{j,1}}I')_{e_j}, 1 \leq j \leq 18$$

$$\textit{r}_{e_{2,j}} \equiv \left(\, \textit{I}_2 \, \rightarrow \, \textit{I}^{\textit{LE}_{j,2}} \, \right)_{e_j} \, , \, 1 \leq j \leq 18$$

 $LE_{j,c}$: ext. inoculation of larvae in compt. j, reprod. cycle c. l_c : aux. obj. to enable inoculation, reprod. cycle c.





Temperatures simulation to start reproductive cycle

Rules

$$r_{e_{3,j,w}} \equiv \left(T_{w} \xrightarrow{\rho_{w+1,j}} \gamma_{w+1} T_{w+1}\right)_{e_{j}} \left\{\begin{array}{l} 1 \leq j \leq 18 \\ 0 \leq w \leq 34, w \neq 19 \end{array}\right.$$

$$r_{e_{4,j,d}} \equiv \left(T_{w} \xrightarrow{1-\rho_{w+1,j}} T_{w+1}\right)_{e_{j}} \left\{\begin{array}{l} 1 \leq j \leq 18 \\ 0 \leq w \leq 34, w \neq 19 \end{array}\right.$$

 $p_{w,j}$: prob. enable reprod. compt. j week w. (Affected by prob. for IT_1 for weeks 1-20 and IT_2 for weeks 21-36, normal prob. func. $N(T_{w,j}, 0.5)$.

 T_d : aux. obj. controlling week.

 γ_w : aux. obj. representing favorable conditions of temperature to start reprod. cycle week w.





Adult movements by vessels

Rules

$$r_{e_{5,s,j,j'}} \equiv (V_s)_{e_j} \xrightarrow{PA_{j,j'}} (V_s')_{e_{j'}} \begin{cases} 1 \leq s \leq 6 \\ 1 \leq j \leq 18 \\ 1 \leq j' \leq 18, j' \neq j \end{cases}$$

$$r_{e_{6,s,j}} \equiv (V_s)_{e_j} \xrightarrow{PA_{j,j}} (V_s')_{e_j} \begin{cases} 1 \leq s \leq 6 \\ 1 \leq j \leq 18 \end{cases}$$

 $PA_{i,j'}$: probab. adult mussel transport from compt. j to j' due to the traffic of vessels.





Viability of eggs

Rules

$$r_{27,m} \equiv \left[O_m \xrightarrow{g_2} \# \right]_0^0, \ 1 \le m \le 36$$

$$r_{28,m} \equiv \left[O_m \xrightarrow{(1-g_2)\cdot(1-mo_1)} L_{1_m} \right]_0^0, \ 1 \le m \le 20$$

$$r_{29,m} \equiv \left[O_m \xrightarrow{(1-g_2)\cdot mo_1} \# \right]_0^0, \ 1 \le m \le 20$$

$$r_{30,m} \equiv \left[O_m \xrightarrow{(1-g_2)\cdot(1-mo_2)} L_{1_m} \right]_0^0, \ 21 \le m \le 36$$

$$r_{31,m} \equiv \left[O_m \xrightarrow{(1-g_2)\cdot mo_2} \# \right]_0^0, \ 21 \le m \le 36$$

 g_2 : % eggs loss (by filtering and predation)

mo_c: mortality of eggs in reproductive cycle *c* (not having fertilized).

 O_m : eggs produced during week m of reproductive cycle.





Movement by hydraulic regime

Rules

$$r_{e_{13,j,m,i,j_{1},\underline{b}}} \equiv \left(L_{m,i,j,j_{1}} \xrightarrow{PR_{m,j_{1},\underline{b}}} L_{m+1,i+1,j,j_{2}}\right)_{e_{j}} \begin{cases} 1 \leq j \leq 18 \\ 1 \leq m \leq 42 \\ 0 \leq i \leq 3 \\ 1 \leq j_{1} \leq 7 \\ 1 \leq j_{2} \leq 7 \end{cases}$$

$$r_{e_{14,j,m,i,j_{1}}} \equiv \left(L_{m,i,j,j_{1}} \xrightarrow{PR_{m,j_{1},8}} \#\right)_{e_{j}} \begin{cases} 1 \leq j \leq 18 \\ 1 \leq m \leq 42 \\ 0 \leq i \leq 3 \\ 8 \leq j_{1} \leq 14 \end{cases}$$

$$r_{e_{27,m,i}} \equiv \left(L_{m,i,18,16} \xrightarrow{0.5} L_{m+1,i+1,18,16}\right)_{e_{18}} \begin{cases} 1 \leq m \leq 42 \\ 0 \leq i \leq 3 \end{cases}$$

$$r_{e_{28,m,i}} \equiv \left(L_{m,i,18,16} \xrightarrow{0.5} L_{m+1,i+1,18,6}\right)_{e_{18}} \begin{cases} 1 \leq m \leq 42 \\ 0 \leq i \leq 3 \end{cases}$$

 $PR_{m,j,j'}$: prob. larvae mov. week m, from compt. j to j'. $L_{m,i,j,j'}$: larvae released week m having spent i+1 weeks in water column, and moved from i to i'.

Recruitment level control

Rules

$$r_{e_{34,j,i}} \equiv \left(\rho_i \rightarrow A_i^{\varphi_j} A R^{2500} \right)_{e_j} \left\{ \begin{array}{l} 1 \leq j \leq 18 \\ 1 \leq i \leq 2 \end{array} \right.$$

 φ_i : capacity compt. j (dep. on types of soil present).

 ρ_i , A_i , AR: aux. objs. to synchronyze carrying capacity and recruitment of young individuals.





MeCoSim app delivery

Process

- Writing P-Lingua model (.pli).
- Setting MeCoSim app config file (.xls).
- Debugging (model, translation, app, simulator).
- Ready to enter scenarios (.ec2) and experimentally validate with experts.
- Once it is validated, run virtual experiments.





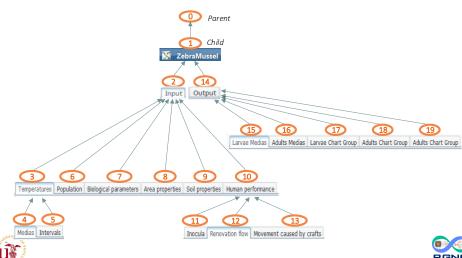
MeCoSim app config I

| Tab ld | Tab Name | Tab Parent Id |
|--------|------------------------------|---------------|
| | 1 Zebra Mussel | 0 |
| | 2 Input | 1 |
| | 3 Temperatures | 2 |
| | 4 Averages | 3 |
| | 5 Intervals | 3 |
| | 6 Population | 2 |
| | 7 Biological parameters | 2 |
| | 8 Area properties | 2 |
| | 9 Soil properties | 2 |
| 1 | 0 Human performance | 2 |
| 1 | 1 Inocula | 10 |
| 10 | 2 Movement caused by crafts | 10 |
| 1 | 3 Movement larvae renovation | 10 |
| 1- | 4 Output | 1 |
| 1 | 5 Larvae Medias | 14 |
| 1 | 6 Adults Medias | 14 |
| 1 | 7 Larvae Chart | 14 |
| 1 | 8 Adults Chart | 14 |
| 1 | 9 AdultsPerAgeChart | 14 |





MeCoSim app config II



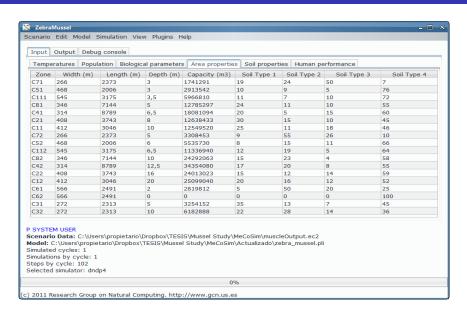
MeCoSim app config III

| Column Id | Column Name | Default Value | Editable | Tooltip |
|-----------|---------------|---------------|----------|---------------|
| 1 | Zone | | TRUE | Zone |
| 2 | Width (m) | | TRUE | Width (m) |
| 3 | Length (m) | | TRUE | Length (m) |
| 4 | Depth (m) | | TRUE | Depth (m) |
| 5 | Capacity (m3) | | TRUE | Capacity (m3) |
| 6 | Soil Type 1 | | TRUE | Soil Type 1 |
| 7 | Soil Type 2 | | TRUE | Soil Type 2 |
| 8 | Soil Type 3 | | TRUE | Soil Type 3 |
| 9 | Soil Type 4 | | TRUE | Soil Type 4 |

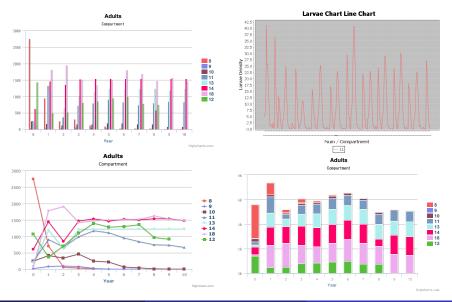




MeCoSim app config IV



MeCoSim app config V



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Conclusions I

Conclusions

- Human beings need to solve problems makes us move forward.
- Unconventional Computing (particularly Membrane Computing) is promising to overcome limitations of electronic technology.
- Software tools are needed so far to simulate the abstract machines, and can aid theorists to deepen in the study of these models of computation.
- They can also be a practical tool for end users to solve problems (theoretical, real-life).





- Design of a methodology for solutions based on P systems.
- Development of MeCoSim, supporting the methodology and helping P systems designers and end users.
- Design and implementation of a plugins architecture for the extensibility of MeCoSim.
- Development and integration of a number of MeCoSim plugins.
- Design of a system of repositories for the community to share plugins, apps, models and scenarios.





Conclusions III

Main contributions II

- Design of a language for simple kernel P systems in P-Lingua framework.
- Development of parser and simulator inside P-Lingua framework.
- Application of the methodology and the developed tools to solve problems (theoretical and real-life).
- Development of MeCoSim web site.





Conclusions IV

MeCoSim web site

MeCoSim Membrane Computing Simulator



MeCoSim installation

Java 1.7 required: included in Path

For Windows and Unix, a MeCoSim shortcut will be created in your desktop. For Mac OS X users, run from McCoSim dir. "CreateShortcut Mac.command".



Overview

MeCoSim (Membrane Computing Simulator) is a software that offers the users analyze and verify different types of models based on P systems. Some of the I

- . Simulation of models of P systems under different initial conditions. It enables the load of P-Lingua based models, parsing, edition, debugging, and different simulation types
- · Visualization capa
- multisets and graph. · Highly customizab
- for each model of a ! · Repositories system
- including plugins, c · Export option for rel
- abstracting P system
- · Plugins architectu
- external non-Java pr · Auto-update capab

Getting started

The best resources to start using MeCoSim : and functionalities:

- · User quide
 - Quick start
 - Installation and first use
 - Custom apps
 - Models Scenarios
 - · Working with models and simulations
 - Debug
 - Simulation
 - · Repositories management
 - · Plugins



Case studies

MeCoSim development started in 2010, and a different areas of interest and application dom studies, grouped by areas. The examples con-MeCoSim. The number of scenarios and the le references to related publications, charts and

- · Case studies
 - · Cell like P systems
 - Tissue like P systems
 - Spiking neural P systems · Population Dynamics P systems







Research groups using MeCoSim I

- Department of Mathematics, Faculty of Life Sciences and Engineering, University of Lleida (Spain)
- Bearded Vulture Study and Protection Group, University of Lleida (Spain)
- Division of Conservation Biology, Institute of Ecology and Evolution, University of Berne Bern (Switzerland)
- Dirección de Medio Ambiente y Desarrollo Sostenible (Endesa)
- Department of Zoology, School of Natural Sciences, Trinity College Dublin (Ireland)
- Department of Animal Production (Division of Wildlife), Faculty of Life Sciences and Engineering, University of Lleida (Spain)





Research groups using MeCoSim II

- Department of Computer Science, University of Sheffield (U.K.)
- Faculty of Mathematics and Computer Science, University of Bucharest (Romania)
- Faculty of Mathematics and Computer Science, University of Pitesti (Romania)
- Key Laboratory of Image Processing and Intelligent Control, Department of Control Science and Engineering, Huazhong University of Science and Technology, Wuhan (China)
- School of Electrical Engineering, Southwest Jiaotong University, Chengdu (China)
- Center of Software Technology and Management Faculty of Information Science and Technology, University Kebangsaan Malaysia (Bangi, Malaysia)





Future work I

- Methodology extensions: uncertainty, data analysis, Data Science.
- Simulation algorithms qualitative improvement: symbolic computation, RETE-like algorithms.
- Extension of the models of computation (e.g. Fuzzy reasoning SNP systems)
 covered (inside-outside Membrane Computing, within Artificial Intelligence).
- Optimization algorithms inclusion in MeCoSim (Evolutionary Membrane Algorithms, etc.).
- Visual definition of P systems: MDE (Model Driven Engineering), Cell Designer or internal development as in MetaPLab.
- Visual controls and buttons to enter scenario info (NetLogo).





Future work II

- Output formats diversification: (gnuplot, json, etc.). In progress.
- Communication protocols standarization for external simulators.
- Non-connected capabilities (requesting simulations and receiving deferred results).
- General mechanism for functions definition for P-Lingua and parameters languages (JSR 223, or SAGE vision).
- Repositories visibility, automatic submission, community increase (Eclipse plugins, NetLogo models library, R language community).
- MeCoSim documentation improvement.





ISI-JCR indexed journals

- M.A. Colomer, A. Margalida, L. Valencia-Cabrera, A. Palau. Application of a computational model for complex fluvial ecosystems: the population dynamics of zebra mussel Dreissena polymorpha as a case study. *Ecological Complexity*, 20 (2014), 116-126. Impact factor: 2.000
- L. Valencia-Cabrera, M. García-Quismondo, M.J. Pérez-Jiménez, Y. Su, H. Yu, L. Pan. Modeling Logic Gene Networks by Means of Probabilistic Dynamic P Systems. *International Journal of Unconventional Computing*, 9, 5-6 (2013), 445-464. Impact factor: 0.684
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- L.F. Macías-Ramos, I. Pérez-Hurtado, M. García-Quismondo, L. Valencia-Cabrera, M.J. Pérez-Jiménez, A. Riscos-Núñez. A P-Lingua based simulator for Spiking Neural P systems. Lecture Notes in Computer Science, 7184 (2012), 257-281.
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- L.F. Macías-Ramos, M.J. Pérez-Jiménez, A. Riscos-Núñez, M. Rius. The efficiency of tissue P systems with cell separation relies on the environment. Lecture Notes in Computer Science, 7762 (2013), 243-256.
- F. Ipate, R. Lefticaru, L. Mierla, L. Valencia-Cabrera, H. Hang, G. Zhang, C. Dragomir, M.J. Pérez-Jiménez, M. Gheorghe. Kernel P systems: Applications and Implementations. *Advances in Intelligent Systems and Computing*, 212 (2013), 1081-1089.
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- I. Pérez-Hurtado, L. Valencia-Cabrera, M.J. Pérez-Jiménez, M.A. Colomer, A. Riscos-Núñez. MeCoSim: A general purpose software tool for simulating biological phenomena by means of P Systems. In K. Li, Z. Tang, R. Li, A.K. Nagar, R. Thamburaj (eds.) Proceedings 2010 IEEE Fifth International Conference on Bio-inpired Computing: Theories and Applications (BIC-TA 2010), IEEE Press, Volume 1, September 23-26, 2010, Changsha, China. pp. 637-643.
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 - Endesa S.A.
- Desarrollo, calibración y validación de un modelo de simulación del comportamiento de las poblaciones del mejillón cebra en embalses. Aplicación al embalse de Ribarroja.
 Endesa S A





My sincere thanks

vă mulțumesc foarte mult pentru atenție

Thank you very much for your attention!
¡Muchas gracias por su atención!





